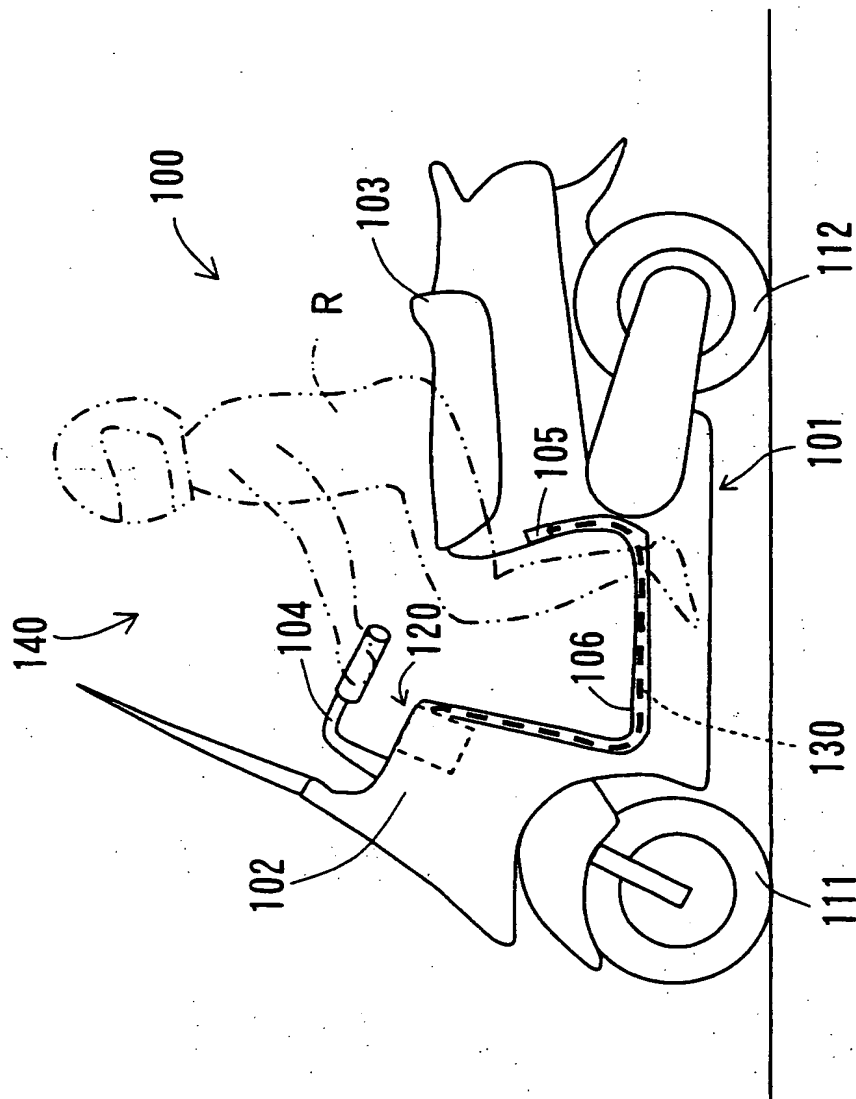
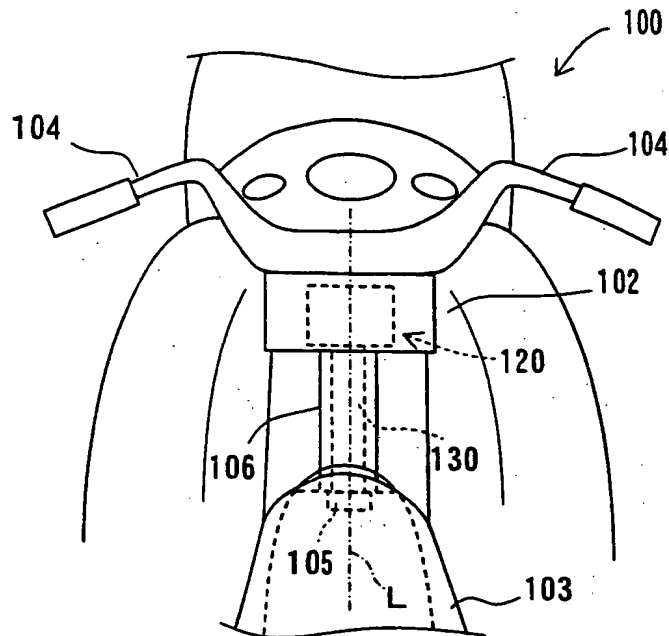


**FIG. 1**

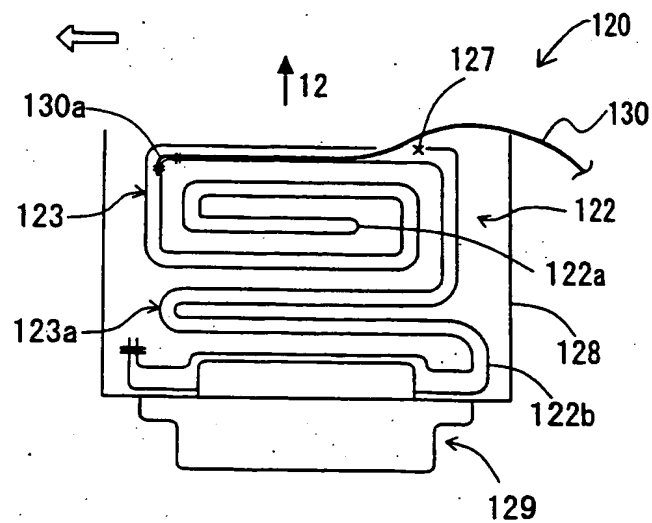


**FIG. 2**



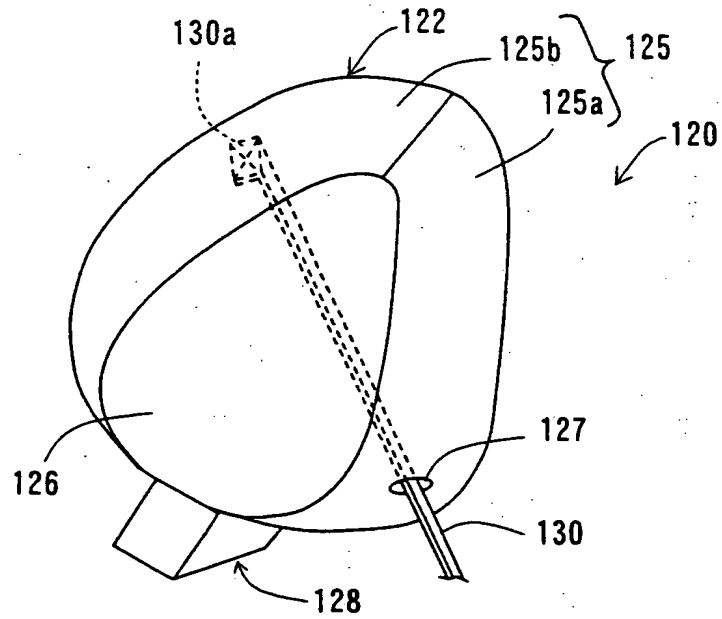
**FIG. 3**

**Vehicle Front**

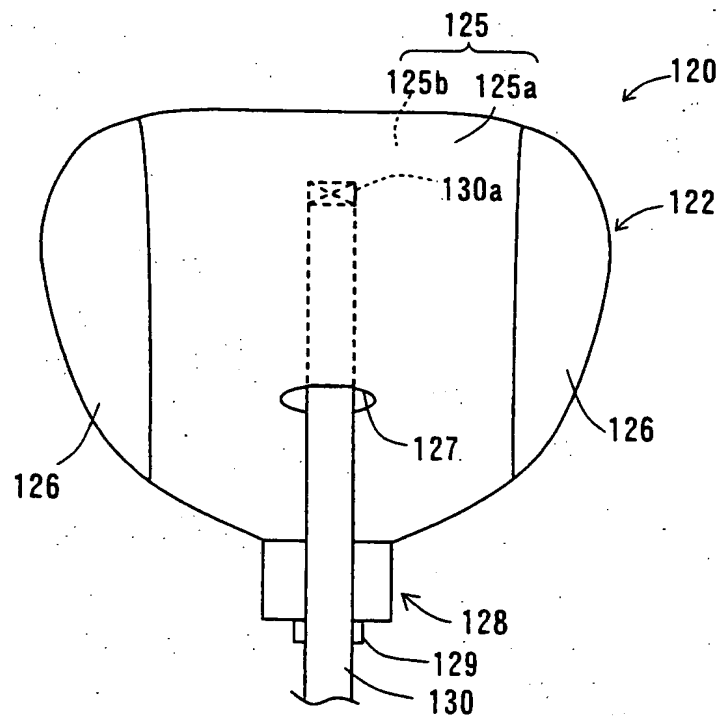


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**FIG. 4**

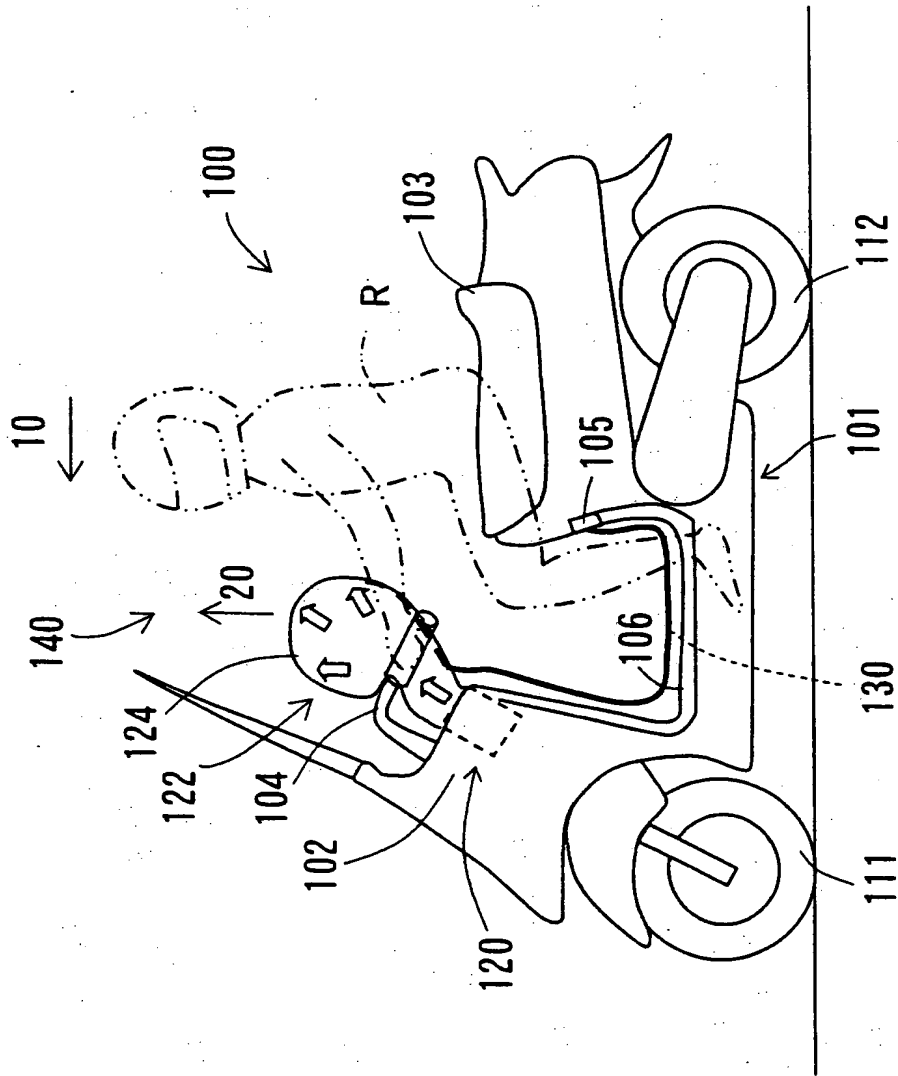


**FIG. 5**

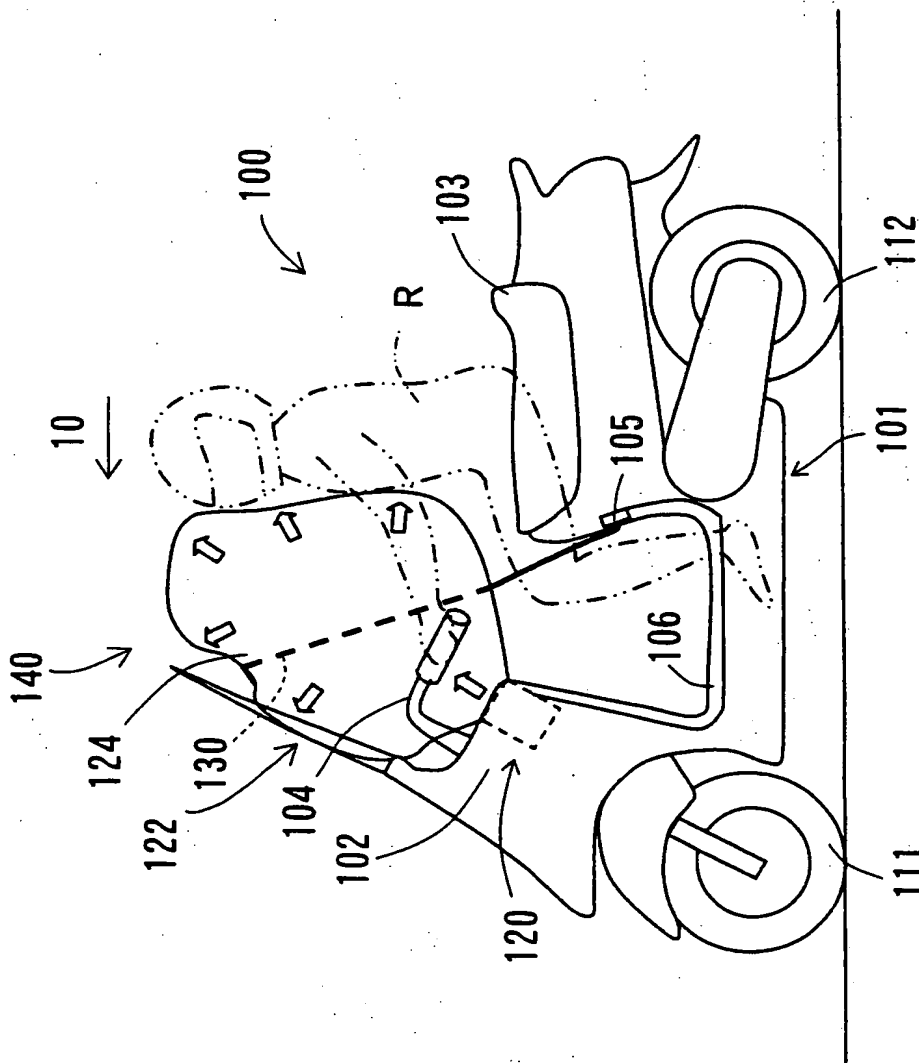


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FIG. 6

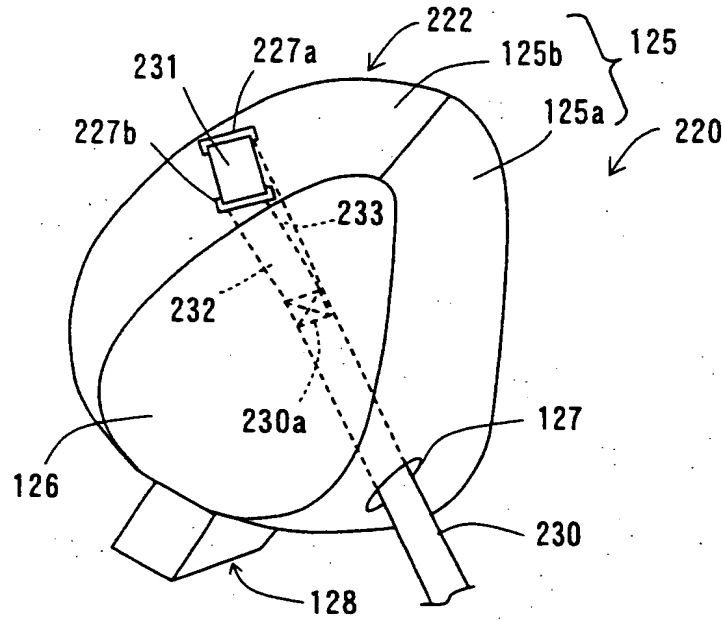


**FIG. 7**

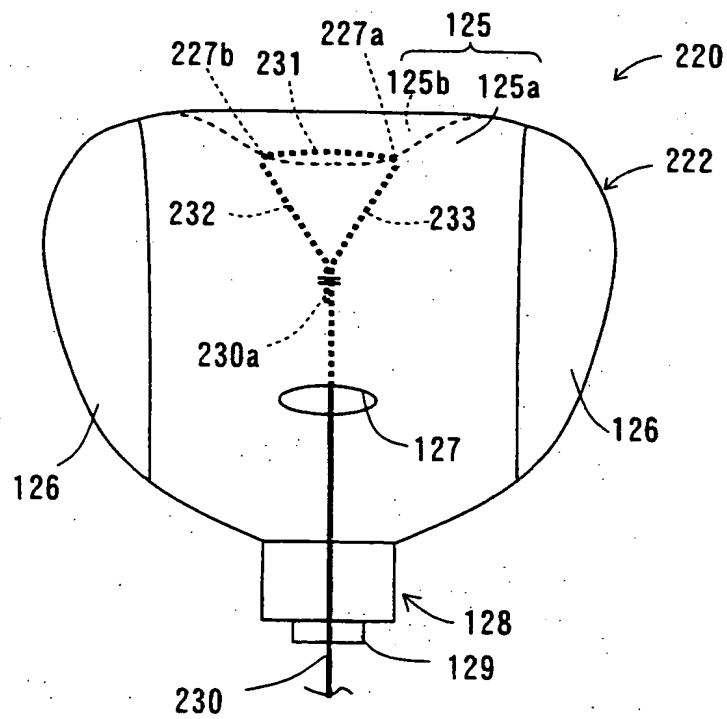


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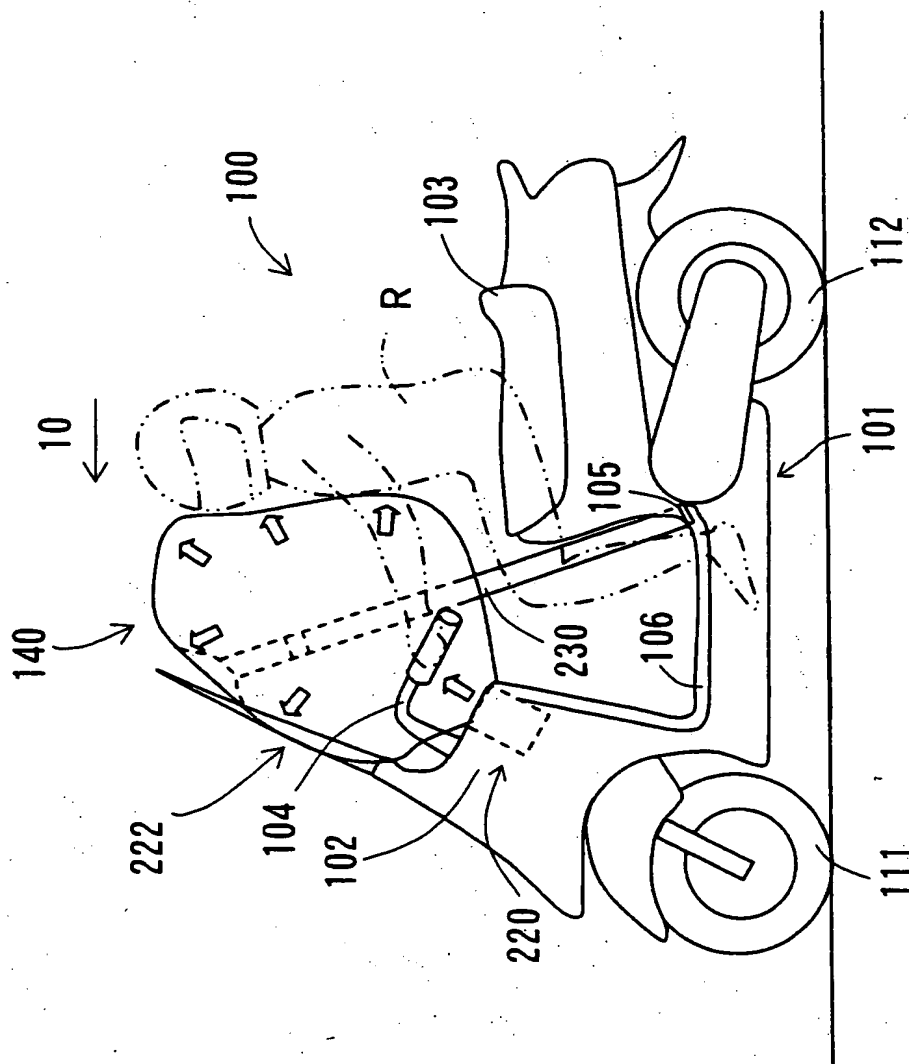
**FIG. 8**



**FIG. 9**

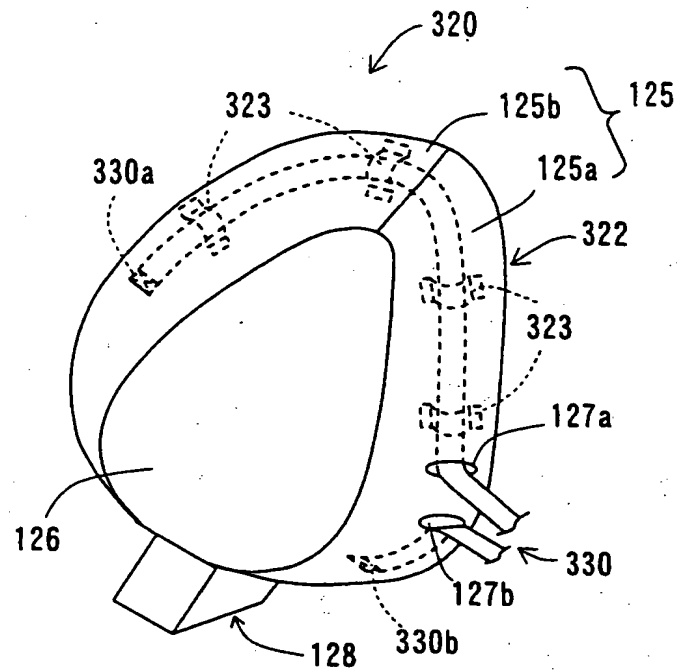


**FIG. 10**



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**FIG. 11**



**FIG. 12**

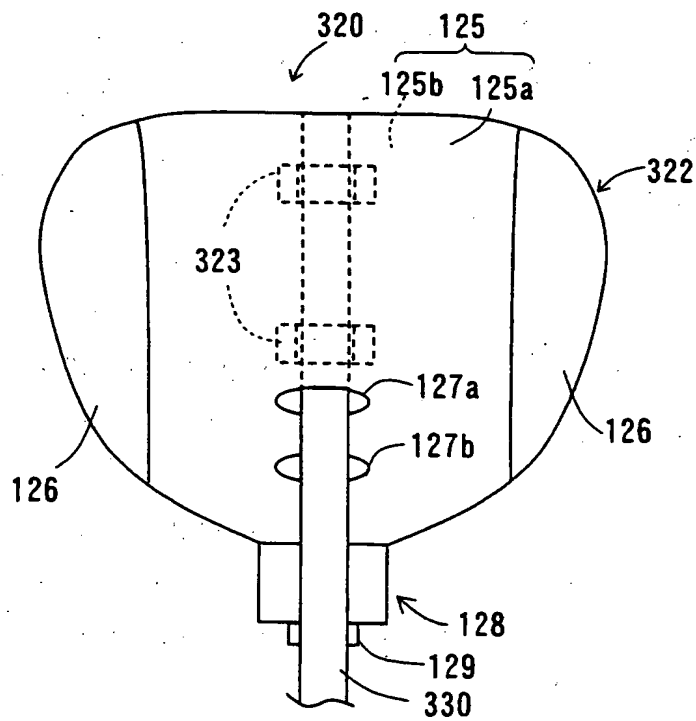




FIG. 10 is a schematic diagram illustrating a system 100 used by a user 10. The user 10 is shown seated at a desk 101, interacting with a device 102. The device 102 is connected to a robotic arm assembly 100. The assembly includes a base 102, a joint 103, a gripper 104, and a sensor 106. A dashed line R indicates a reach or path. Other components labeled include 111, 112, 320, 330, and 305.

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**FIG. 14**

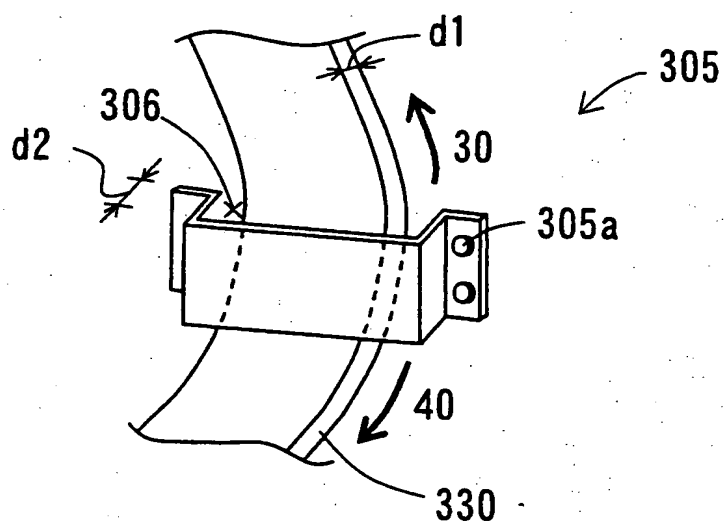
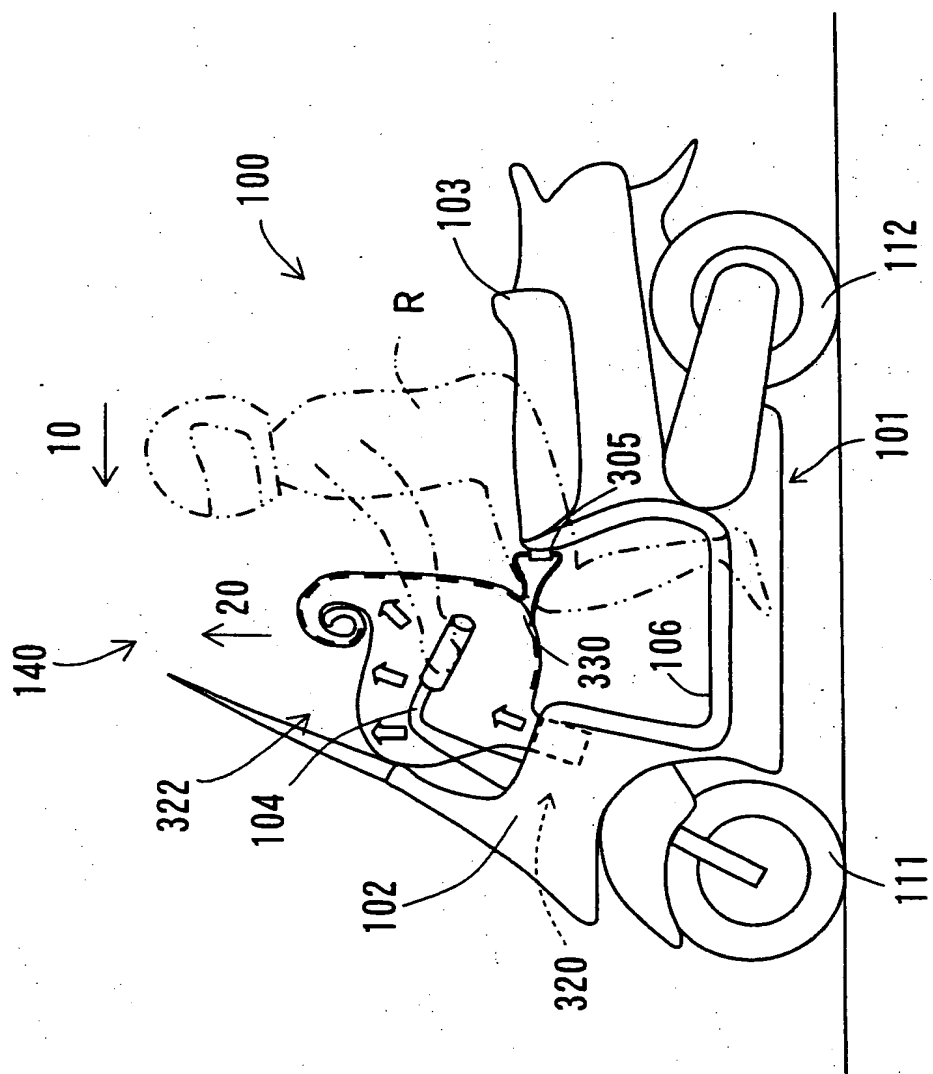


FIG. 15



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FIG. 16

